Stellar/Planetary Atmospheres Part 05: Numerical RT I

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Topics

- Numerical RT part 1
 - The operator splitting method
 - a method for the FS
 - computing Λ*

Numerical solution

- there are many numerical RT methods
- too many to describe them all
 - direct methods
 - iterative methods
- all methods need to deal with scattering!
- here: I will describe the currently most used method

Numerical solution

• recap: scattering \rightarrow

$$S = (1 - \epsilon)J + \epsilon B$$
$$\epsilon = \frac{\kappa}{\kappa + \sigma}$$

- ► S depends on B and (unknown) J
- ightarrow
 ightarrow self-consistent solution for J required
- direct solution expensive
- use iterative method
- eigenvalues of iteration matrix close to unity

 \rightarrow use operator splitting to reduce eigenvalues of amplification matrix

Formal solution (how? see below!)

$$J = \Lambda S$$

Λ-iteration:

$$ar{J}_{
m new} = \Lambda S_{
m old}, \quad S_{
m new} = (1-\epsilon)ar{J}_{
m new} + \epsilon B$$

 \blacktriangleright does not work for $\tau >> 1$ & small ϵ

Solution: Split Λ operator

$$\Lambda=\Lambda^*+(\Lambda-\Lambda^*)$$

 \blacktriangleright \rightarrow iteration procedure

$$ar{J}_{
m new} = \Lambda^* S_{
m new} + (\Lambda - \Lambda^*) S_{
m old}$$

using
$$S = (1 - \epsilon)J + \epsilon B$$
 and $\bar{J}_{\rm fs} = \Lambda S_{
m old}$
 gives

$$\left[1 - \Lambda^*(1 - \epsilon)
ight] ar{J_{
m new}} = ar{J_{
m fs}} - \Lambda^*(1 - \epsilon)ar{J_{
m old}}$$

• solved directly to obtain \bar{J}_{new}

$$ar{J}_{ ext{new}} = \left[1 - \Lambda^*(1-\epsilon)
ight]^{-1} ig(ar{J}_{ ext{fs}} - \Lambda^*(1-\epsilon)ar{J}_{ ext{old}}ig)$$

mathematically:

- same family as Jacobi or Gauss-Seidel methods
- general form

$$Mx^{k+1} = Nx^k + b$$

for solution of linear system

$$Ax = b$$

with

$$A = M - N$$

 \blacktriangleright operator splitting \rightarrow

$$M = 1 - \Lambda^*(1 - \epsilon)$$

 and

$$N = (\Lambda - \Lambda^*)(1 - \epsilon)$$

for the system matrix

$$A = 1 - \Lambda(1 - \epsilon)$$

- \blacktriangleright convergence of the iterations \rightarrow
- ▶ spectral radius ρ(G) < 1</p>
- with amplification matrix

$$G=M^{-1}N$$

for this to help

- \blacktriangleright eigenvalues of amplification matrix ${\it G} \ll 1$
- works best if $\Lambda^* = \Lambda$ (direct solution, how? see below!)
- \rightarrow expensive (?)
- ► diagonal Λ^{*} → simple but slow convergence
- ► band-matrix $\Lambda^* \rightarrow$ rapid convergence, harder to construct

- many possible ways to construct Λ^*
- best: elements of Λ itself
 - no estimates/free parameters
 - 'easy' to compute & use
 - build band-matrix Λ*

▶ pp RTE:

$$\mu \frac{dI}{d\tau_r} = I - S$$

- discretize τ_r (spatial) space
- discretize μ (angle) space
- light path \rightarrow lines of constant μ

- $\blacktriangleright \rightarrow$ characteristics of the RTE
- along a characteristic

$$\frac{dI}{d\tau} = I - S$$

• where $I = I(\mu)$ and $\tau = \tau_r/\mu$ are now measured along the characteristic

spherical geometry:

$$\mu \frac{\partial I}{\partial r} + \frac{1 - \mu^2}{r} \frac{\partial I}{\partial \mu} = \chi(S - I)$$

- characteristics = light paths
- \blacktriangleright static medium \rightarrow straight lines
- parameterized by impact parameter p

$$\mu(r) = \pm \sqrt{1 - p^2/r^2}$$

gives μ for each point along the characteristic p

- \blacktriangleright \rightarrow along a characteristic μ varies in spherical geometry
- but the RTE along the characteristic looks like

$$\frac{dI}{d\tau} = I - S$$

• where $I = I(\mu(p))$ and τ are now measured along the characteristic

- $\blacktriangleright \rightarrow$ spherical and pp cases reduced to FS along the characteristic
- J computed by numerical quadrature
- need to compute I along the characteristics
- basic idea:
 - approximate S along the characteristic by piece-wise linear or parabolic functions
 - analytically solve FS along the characteristic for I

this scheme gives

$$I(\tau_{i}) = I(\tau_{i-1}) \exp(\tau_{i-1} - \tau_{i}) + \int_{\tau_{i-1}}^{\tau_{i}} S(\tau) \exp(\tau - \tau_{i}) d\tau$$

$$I(\tau_{i}) \equiv I_{i-1} \exp(-\Delta \tau_{i-1}) + \Delta I_{i}$$

- ► τ_i denotes the optical depth along the ray with $\tau_1 \equiv 0$ and τ_{i-1}
- $\blacktriangleright \ \tau$ is calculated using piecewise linear interpolation of χ along the ray

$$\Delta \tau_{i-1} = (\chi_{i-1} + \chi_i) |s_{i-1} - s_i|/2$$

 S(τ) along a characteristic is interpolated by linear or parabolic polynomials so that

$$\Delta I_i = \alpha_i S_{i-1} + \beta_i S_i + \gamma_i S_{i+1}$$

with

$$\begin{aligned} \alpha_i &= \mathbf{e}_{0i} + [\mathbf{e}_{2i} - (\Delta \tau_i + 2\Delta \tau_{i-1})\mathbf{e}_{1i}] / [\Delta \tau_{i-1} (\Delta \tau_i + \Delta \tau_{i-1})] \\ \beta_i &= [(\Delta \tau_i + \Delta \tau_{i-1})\mathbf{e}_{1i} - \mathbf{e}_{2i}] / [\Delta \tau_{i-1} \Delta \tau_i] \\ \gamma_i &= [\mathbf{e}_{2i} - \Delta \tau_{i-1}\mathbf{e}_{1i}] / [\Delta \tau_i (\Delta \tau_i + \Delta \tau_{i-1})] \end{aligned}$$

for parabolic interpolation and

$$\begin{array}{rcl} \alpha_i &=& e_{0i} - e_{1i} / \Delta \tau_{i-1} \\ \beta_i &=& e_{1i} / \Delta \tau_{i-1} \\ \gamma_i &=& 0 \end{array}$$

for linear interpolation.

auxiliary functions:

$$\begin{array}{rcl} e_{0i} & = & 1 - \exp(-\Delta \tau_{i-1}) \\ e_{1i} & = & \Delta \tau_{i-1} - e_{0i} \\ e_{2i} & = & (\Delta \tau_{i-1})^2 - 2e_{1i} \end{array}$$

- $\Delta \tau_i \equiv \tau_{i+1} \tau_i$ is the optical depth along the characteristic
- must use linear coefficients at the last integration point along each ray
- some times linear may be better than parabolic (why?)

- spherical case:
 - ► tangent rays: FS starts at point 2 with *I*₁ given as the outer BC and proceeds along the ray
 - ► FS for 'core-intersecting' ray: split into two parts:
 - 1. integration from point 1 to point N, where I_1 is given as the outer boundary condition and
 - 2. integration from point N + 2 to point 2N, where I_{N+1} is given as the inner boundary condition.
- pp case: like 'core intersecting' spherical case

- \blacktriangleright with this procedure, the I's can be computed for given S
- for all characteristics \rightarrow full RF is known
- could be used for Λ iteration for $\epsilon \approx 1$
- next step: devise procedure to compute Λ^* !
- space-discretized \rightarrow
 - $\Lambda \text{ operator} \to \Lambda \text{ matrix}$

basic idea:

- set S = (0, ..., 1, 0, ...)
- perform FS
- \rightarrow delivers one column of Λ matrix
- repeat for all spatial (radial) points
- \rightarrow compute Λ matrix
- if done like described \rightarrow very expensive!
- however, it can be done analytically!

- describe spherical case
- \blacktriangleright pp case \rightarrow just consider 'core intersecting' characteristics

$$\Lambda^* = \Lambda^t + \Lambda^c$$

- Λ^t: contributions from tangential characteristics
- Λ^c: contributions from core intersecting characteristics
- do not construct full Λ matrix (time!)
- construct tri-diagonal Λ*

- Λ^t construction
- 1 or 2 intersection of tangential characteristics with radial grid points
- label characteristic tangent to shell i + 1 with the index i
- \rightarrow construction of Λ^t contributions

$$\begin{aligned} \bullet & (a) \ 1 < j \le i \\ & \Lambda_{j-1,j}^t \ += \ \sum_i \left(w_{j-1,i} s_{1,i} + w_{k+1,i} s_{6,i} \right) \\ & \Lambda_{j,j}^t \ += \ \sum_i \left(w_{j,i} s_{2,i} + w_{k,i} s_{5,i} \right) \\ & \Lambda_{j+1,j}^t \ += \ \sum_i \left\{ \begin{pmatrix} w_{j+1,i} s_{3,i} + w_{k-1,i} s_{4,i} \end{pmatrix} & \text{for } i \neq j \\ & w_{k-1,i} s_{4,i} \end{pmatrix} & \text{for } i = j \end{aligned}$$

with k = 2(i-1) - j and

$$s_{1,i} = \gamma_{j-1,i}$$

$$s_{2,i} = s_{1,i} \exp(-\Delta \tau_{j-1,i}) + \beta_{j,i}$$

$$s_{3,i} = s_{2,i} \exp(-\Delta \tau_{j,i}) + \alpha_{j+1,i}$$

$$s_{4,i} = s_{3,i} \exp(-\Delta \tau_{j+1 \to k-1,i}) + \gamma_{k-1,i}$$

$$s_{5,i} = s_{4,i} \exp(-\Delta \tau_{k-1,i}) + \beta_{k,i}$$

$$s_{6,i} = s_{5,i} \exp(-\Delta \tau_{k,i}) + \alpha_{k+1,i}$$

$$(b) j = 1$$

$$\Lambda_{1,1}^{t} += \sum_{i} (w_{1,i}s_{2,i} + w_{k,i}s_{5,i})$$

$$\Lambda_{2,1}^{t} += \sum_{i} \begin{cases} (w_{2,i}s_{3,i} + w_{k-1,i}s_{4,i}) & \text{for } i \neq 1, \\ w_{k-1,i}s_{4,i} & \text{for } i = 1, \end{cases}$$

with k = 2i + 1 and

$$s_{2,i} = \beta_{1,i}$$

$$s_{3,i} = s_{2,i} \exp(-\Delta \tau_{1,i}) + \alpha_{2,i}$$

$$s_{4,i} = s_{3,i} \exp(-\Delta \tau_{2 \to k-1,i}) + \gamma_{k-1,i}$$

$$s_{5,i} = s_{4,i} \exp(-\Delta \tau_{k-1,i}) + \beta_{k,i}$$

$$s_{6,i} = s_{5,i} \exp(-\Delta \tau_{k,i}) + \alpha_{k+1,i}$$

• (c)
$$j = i + 1$$
 (point of tangency)

$$egin{array}{rcl} \Lambda_{i,i+1}^t & += & \sum_i \left(w_{i,i} s_{1,i} + w_{i+2,i} s_{3,i}
ight) \ \Lambda_{i+1,i+1}^t & += & \sum_i w_{i,i} s_{2,i} \end{array}$$

$$s_{1,i} = \gamma_{i,i} s_{2,i} = s_{1,i} \exp(-\Delta \tau_{i,i}) + \beta_{i+1,i} s_{3,i} = s_{2,i} \exp(-\Delta \tau_{i+1,i}) + \alpha_{i+1,i}$$

- $\Delta \tau_{j+1 \rightarrow k-1, i}$: optical depth along the characteristic
- $w_{j,i}$: μ quadrature weights
- can be extended to full Λ matrix!
- core intersecting characteristics: simplified version of above
- this method can be used also in moving media
- can be extended to line transfer (later)

Convergence: static



Convergence: expanding



relative Performance



- SN: $v_{\text{max}} = 0.13c$, extension 100
- Fireball: $v_{\text{max}} = 0.9c$, extension 10^6
- +: Cray Y/MP C90, *: Cray-2, other: IBM 3090-500E VF

relative Performance



▶ historical ... ca. 1993